

### CONTEXT

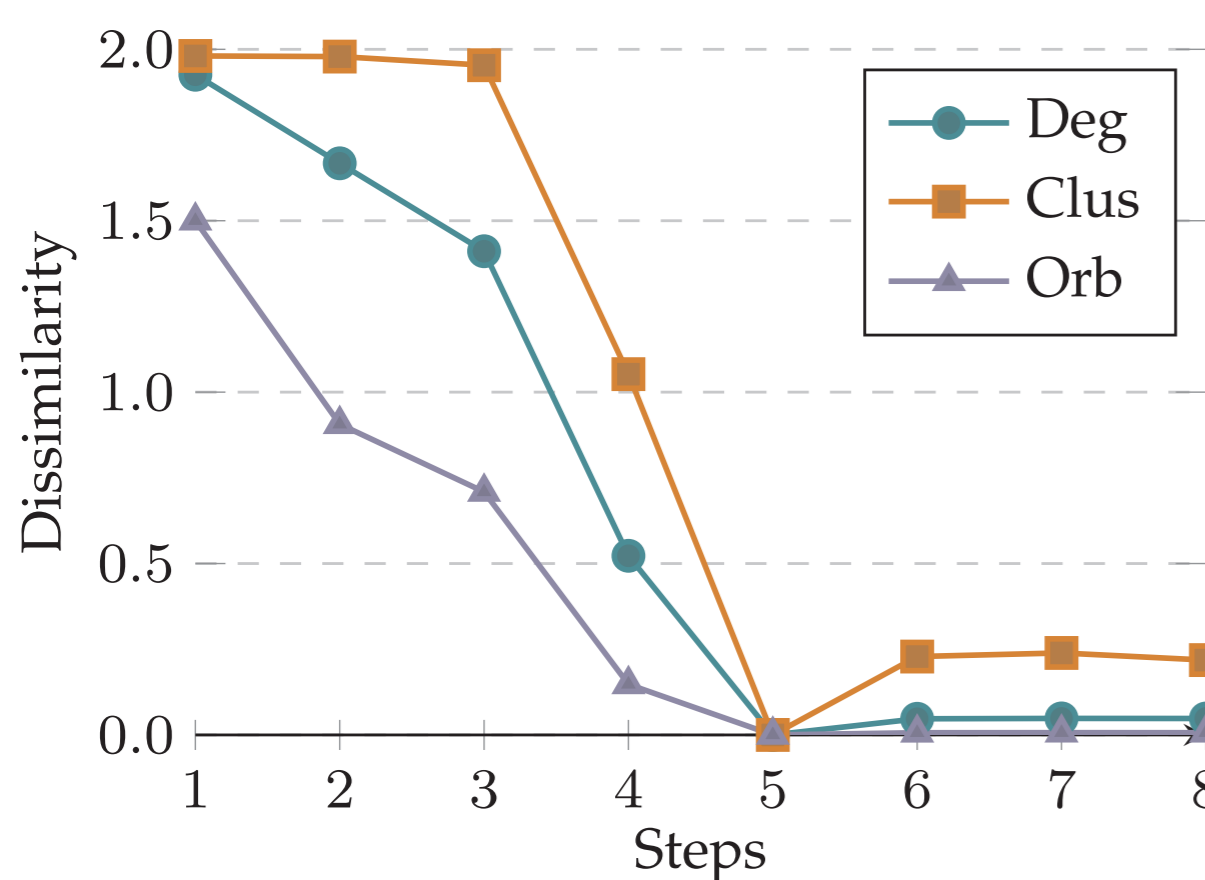
**Problem.** Current deep learning graph-models do not support extreme variations: complete changes in the structure of graphs in each layer.

**Proposal.** Use graph convolutions to propose expected node features, and predict the best structure based on them. Recursively repeat these steps to enhance the prediction and the embeddings.

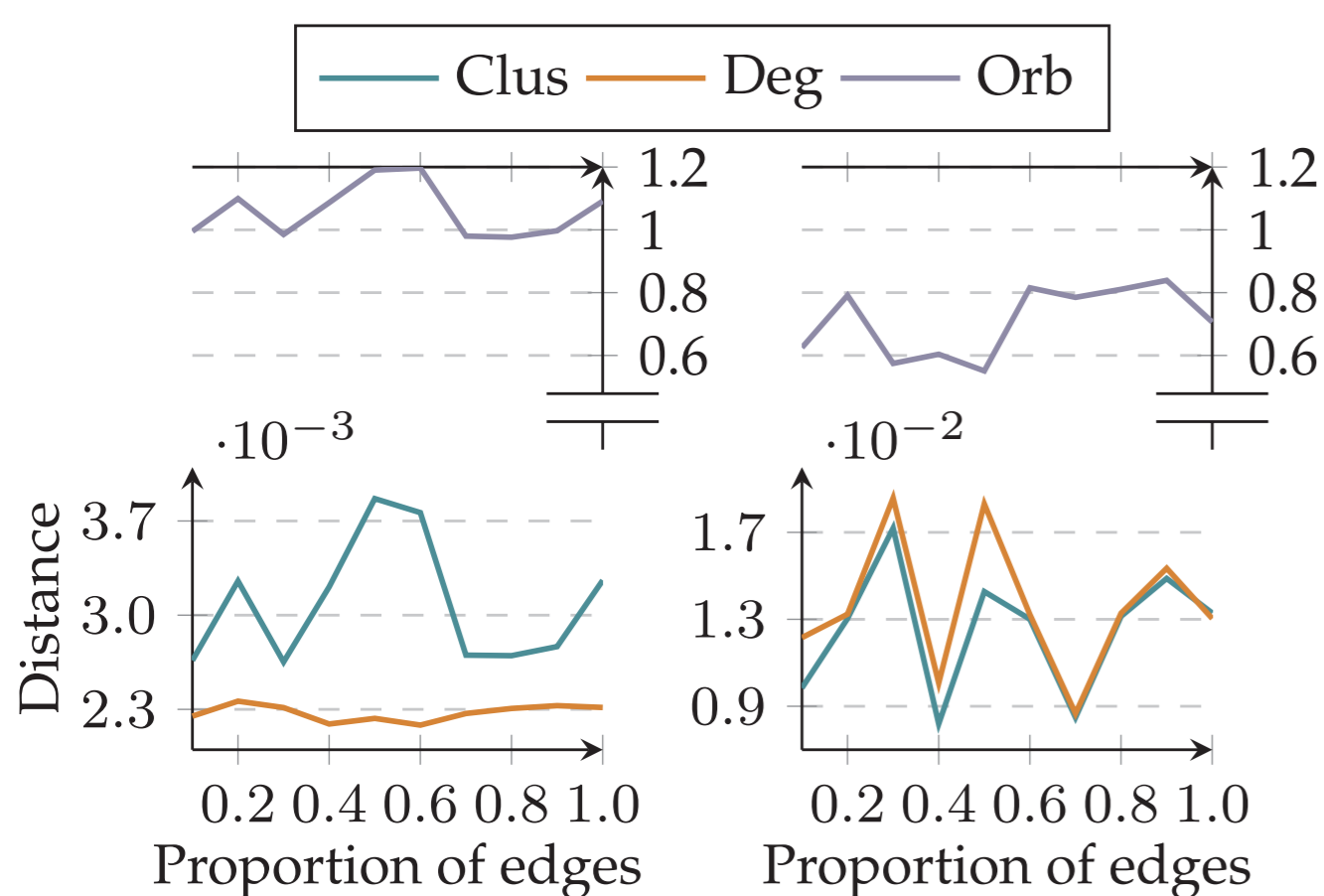
### CONTRIBUTIONS

- Two prediction functions: nodes' features and adjacency
- A recurrent architecture
- An end-to-end learning framework for predicting graphs' structure
- Introduction of new synthetic datasets, i.e., 3D surface functions and geometric images

### ANALYSIS



Dissimilarity MMD between pred. and GT (smaller is better) on the 3D Surface.

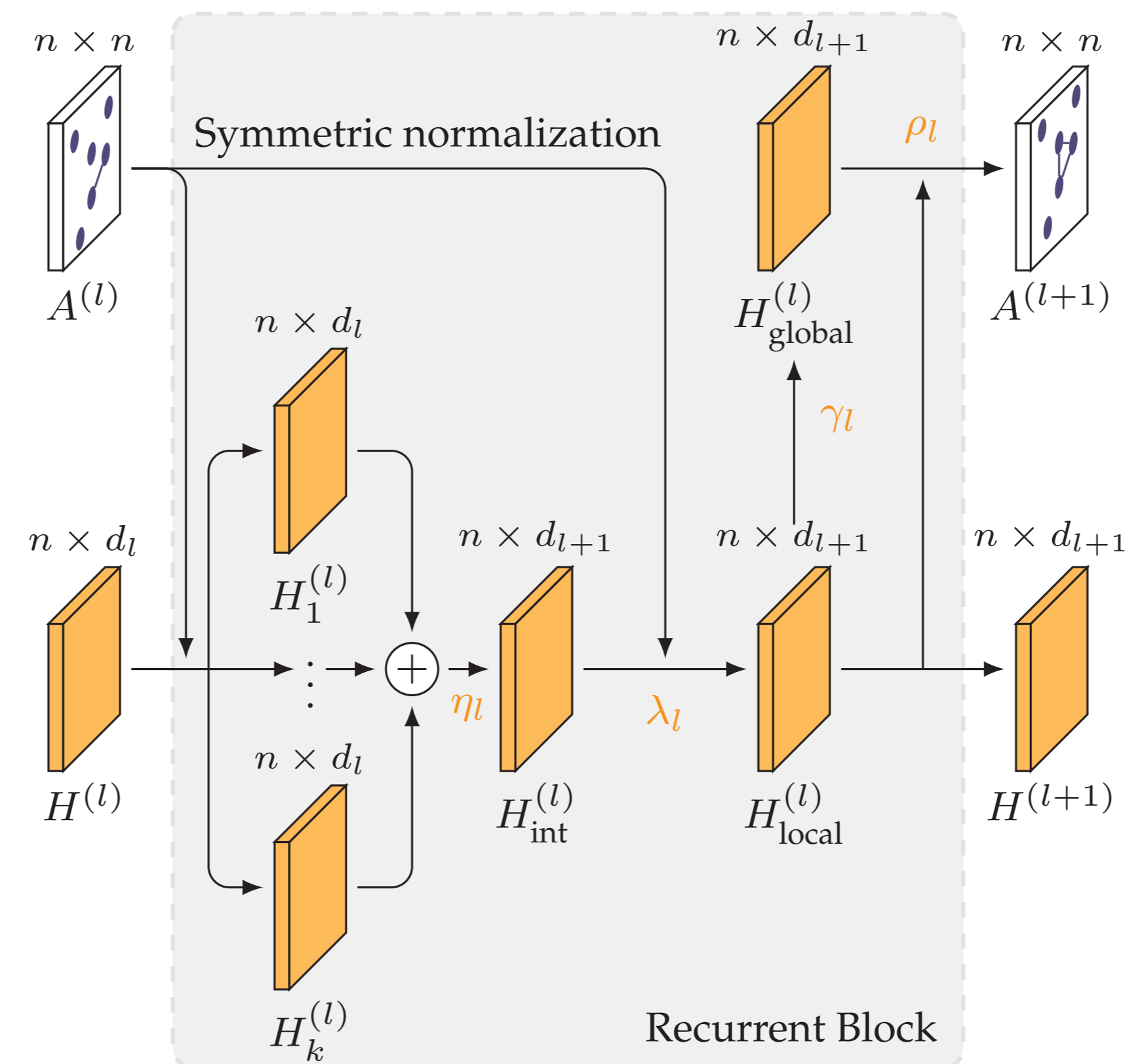


MMD varying the input structure on Community  $C = 4$  (left) and  $C = 2$  (right).




Losses			Metrics					
IoU	HED	Reg	Acc $\uparrow$	IoU $\uparrow$	Dice $\uparrow$	Deg $\downarrow$	Clus $\downarrow$	Orb $\downarrow$
-	✓	-	0.9997	0.9747	0.9872	0.0068	0.0011	0.1069
-	✓	✓	0.9997	0.9749	0.9872	0.0065	0.0010	0.0972
✓	-	-	0.7997	0.0524	0.0996	1.8624	1.9980	0.9827
✓	-	✓	0.8938	0.0953	0.1740	1.7689	1.9491	1.1862
✓	✓	-	0.9997	<b>0.9749</b>	<b>0.9872</b>	0.0063	0.0002	0.0619
✓	✓	✓	<b>0.9997</b>	0.9749	0.9872	<b>0.0062</b>	<b>0.0002</b>	<b>0.0053</b>

Ablation of GLN using Geometric Figures.

### PROPOSED METHOD: GLN



#### Loss Functions:

-  Intersection over Union (IoU) of adjacency
-  Class-balanced Cross-Entropy (HED)
-  Regularization

$$H_{\text{int}}^{(l)} = \sum_{i=1}^k \sigma_l \left( \hat{A}^{(l)} H_i^{(l)} W_i^{(l)} \right)$$

$$H_{\text{local}}^{(l)} = \sigma_l \left( \hat{A}^{(l)} H_{\text{int}}^{(l)} U^{(l)} \right)$$

$$H_{\text{global}}^{(l)} = \sigma_l \left( H_{\text{local}}^{(l)} Z^{(l)} \right)$$

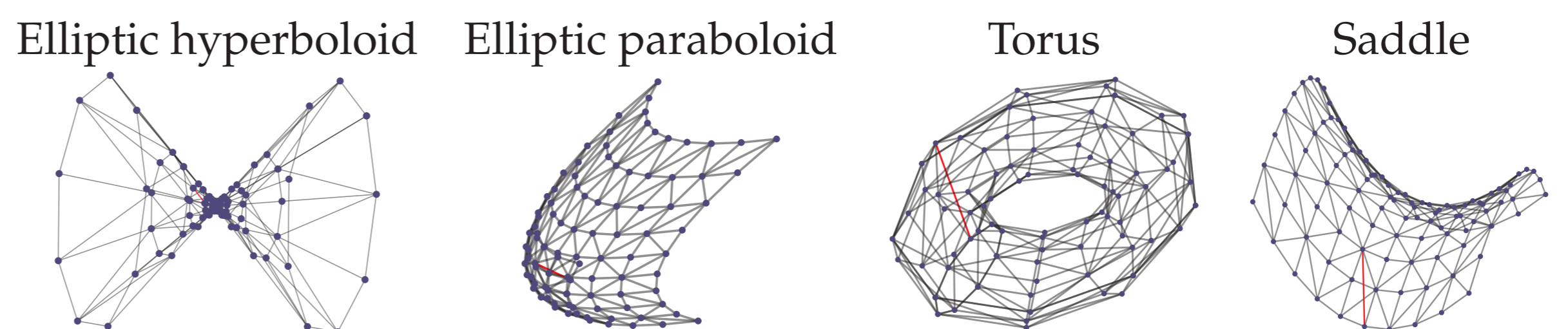
$$A^{(l+1)} = \sigma_l \left( M^{(l)} H_{\text{local}}^{(l)} Q^{(l)} H_{\text{global}}^{(l) \top} M^{(l) \top} \right)$$

 Learnable matrices

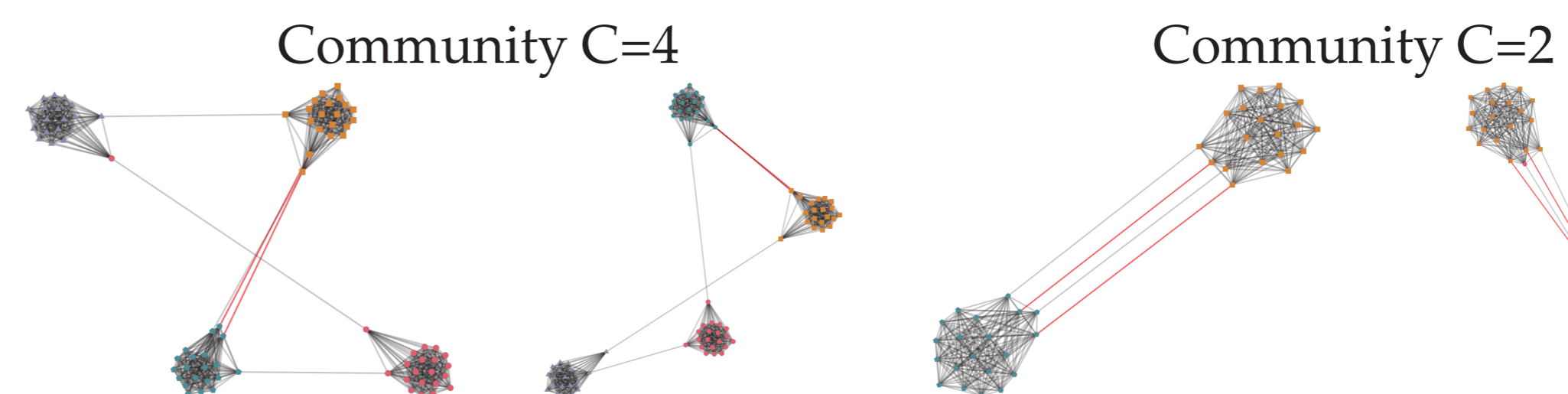
 Non linearities

 Embedding functions

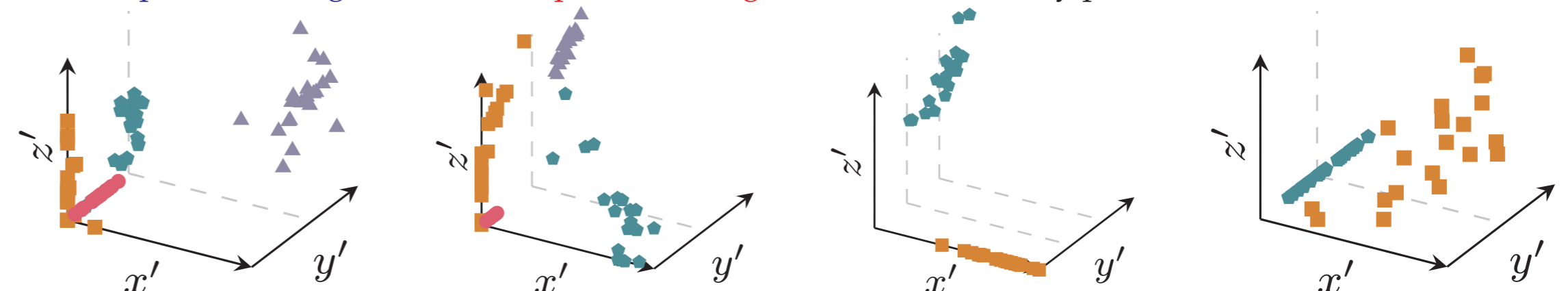
### RESULTS



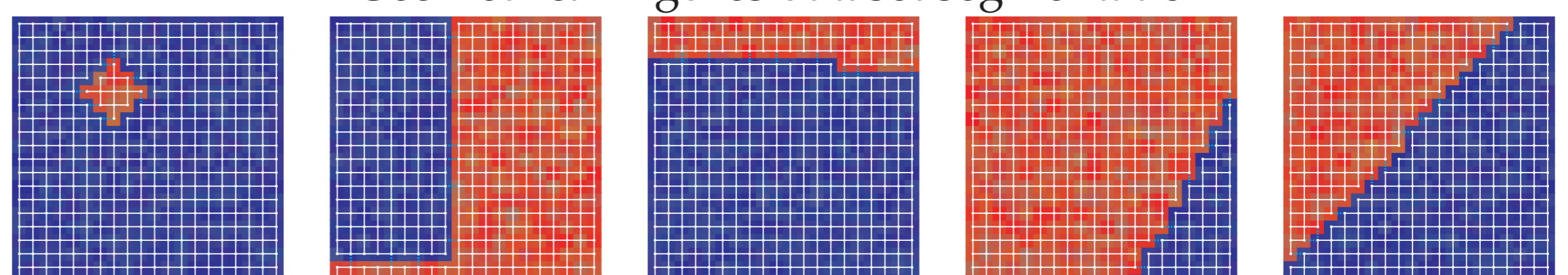
 Not predicted edges (FN),  extra predicted edges (FP), and correctly predicted ones.



 Not predicted edges (FN),  extra predicted edges (FP), and correctly predicted ones.



#### Geometrical Figures dataset segmentation



 Not predicted edges (FN),  extra predicted edges (FP), and correctly predicted ones.