
Chapter 3

Instructions: Language of the Machine

Instructions:

- **Language of the Machine**
- **More primitive than higher level languages**
 - e.g., no sophisticated control flow
- **Very restrictive**
 - e.g., **MIPS Arithmetic Instructions**
- **We'll be working with the MIPS instruction set architecture**
 - similar to other architectures developed since the 1980's
 - used by NEC, Nintendo, Silicon Graphics, Sony

Design goals: maximize performance and minimize cost, reduce design time

3.2 MIPS arithmetic

- All instructions have 3 operands
- Operand order is fixed (destination first)

Example:

C code: **A = B + C**

MIPS code: **add \$s0, \$s1, \$s2**

(associated with variables by compiler)

MIPS arithmetic

- Design Principle: simplicity favors regularity. Why?
- Of course this complicates some things...

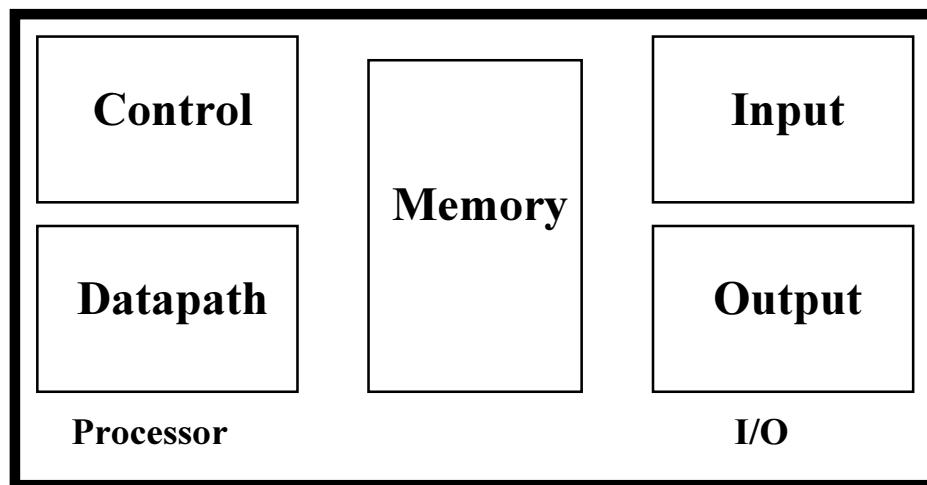
C code: **A = B + C + D;**
 E = F - A;

MIPS code: **add \$t0, \$s1, \$s2**
 add \$s0, \$t0, \$s3
 sub \$s4, \$s5, \$s0

- Operands must be registers, only 32 registers provided
- Design Principle: smaller is faster. Why?

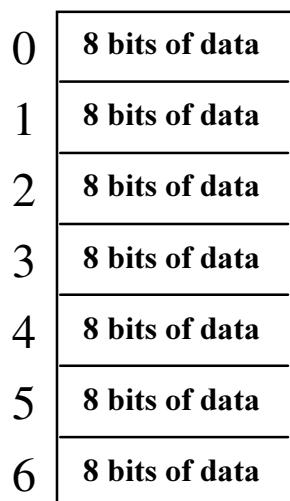
Registers vs. Memory (3.3)

- Arithmetic instructions operands must be registers,
 - only 32 registers provided (32 bits)
- Compiler associates variables with registers
- What about programs with lots of variables



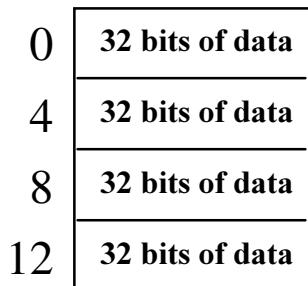
Memory Organization

- Viewed as a large, single-dimension array, with an address.
- A memory address is an index into the array
- "Byte addressing" means that the index points to a byte of memory.



Memory Organization

- Bytes are nice, but most data items use larger "words"
- For MIPS, a word is 32 bits or 4 bytes.



Registers hold 32 bits of data

- 2^{32} bytes with byte addresses from 0 to $2^{32}-1$
- 2^{30} words with byte addresses 0, 4, 8, ... $2^{32}-4$
- Words are aligned
 - i.e., what are the least 2 significant bits of a word address?

Instructions

- **Load and store instructions**
- **Example:**

C code: $A[8] = h + A[8];$

MIPS code: `lw $t0, 32($s3)`
 `add $t0, $s2, $t0`
 `sw $t0, 32($s3)`

- **Store word has destination last**
- **Remember arithmetic operands are registers, not memory!**
(isto é chamado de arquitetura “load-store”)

Exemplo com array (pag. 114)

- Seja $g = h + A[i]$;
onde A é um array de 100 palavras com base apontada por $\$s3$ e o compilador associa as variáveis g , h e i com os registradores:
 - $g: \$s1$
 - $h: \$s2$
 - $i: \$s4$
- Antes de $\$t1 \leftarrow A[i]$ é necessário calcular o endereço do elemento ($A+4*i$):
$$\begin{aligned} &(\text{multiply}) \quad \$t1, \quad \$s4, \quad (\text{valor } 4) \\ &\text{add } \$t1, \quad \$s3, \quad \$t1 \end{aligned}$$
- Agora é possível ler o endereço apontado por $\$t1$ e executar a soma
$$\begin{aligned} &\text{lw } \$t0, \quad 0(\$t1) \quad \# \text{temp } \$t0 \leftarrow A[i] \\ &\text{add } \$s1, \quad \$s2, \quad \$t0, \quad \# \quad g \leftarrow h + A[i] \end{aligned}$$

Our First Example

- Can we figure out the code?

```
swap(int v[], int k);
{ int temp;
    temp = v[k]
    v[k] = v[k+1];
    v[k+1] = temp;
}
                                swap:

    muli $2, $5, 4
    add $2, $4, $2
    lw $15, 0($2)
    lw $16, 4($2)
    sw $16, 0($2)
    sw $15, 4($2)
    jr $31
```

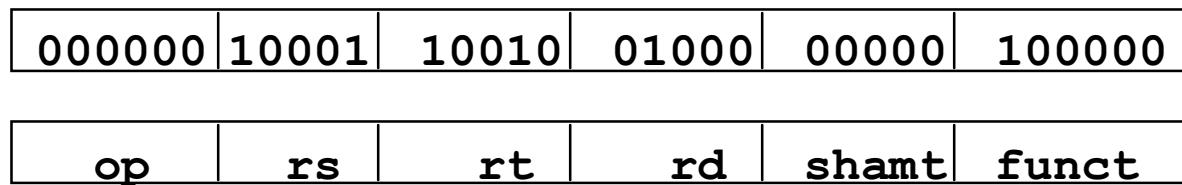
So far we've learned:

- MIPS
 - loading words but addressing bytes
 - arithmetic on registers only

| <u>Instruction</u> | <u>Meaning</u> |
|----------------------|----------------------------------|
| add \$s1, \$s2, \$s3 | $\$s1 = \$s2 + \$s3$ |
| sub \$s1, \$s2, \$s3 | $\$s1 = \$s2 - \$s3$ |
| lw \$s1, 100(\$s2) | $\$s1 = \text{Memory}[\$s2+100]$ |
| sw \$s1, 100(\$s2) | $\text{Memory}[\$s2+100] = \$s1$ |

Machine Language (3.4)

- Instructions, like registers and words of data, are also 32 bits long
 - Example: add \$t0, \$s1, \$s2
 - registers have numbers, \$t0=8, \$s1=17, \$s2=18
- Instruction Format (TIPO R):



- Can you guess what the field names stand for?
 - rs: source register
 - rt: target register
 - rd: destination register
 - op + funct: definem a instrução

Machine Language

- Consider the load-word and store-word instructions,
 - What would the regularity principle have us do?
 - New principle: Good design demands a compromise
- Introduce a new type of instruction format
 - I-type for data transfer instructions
 - other format was R-type for register
- Example: `lw $t0, 32($s2)`

| | | | |
|----|----|----|---------------|
| 35 | 18 | 9 | 32 |
| op | rs | rt | 16 bit number |

- Where's the compromise?

Formatos de instrução já vistos

| Instrução | Formato | op | rs | rt | rd | shamt | funct | address |
|------------|---------|----|-----|-----|-----|-------|-------|---------|
| add | R | 0 | reg | reg | reg | 0 | 32 | - |
| sub | R | 0 | reg | reg | reg | 0 | 42 | - |
| lw | I | 35 | reg | reg | - | - | - | address |
| sw | I | 45 | reg | reg | - | - | - | address |

Exemplo (pag 119)

C code: **A[300] = h + A[300];**

MIPS code:

```
lw $t0, 1200($t1)
add $t0, $s2, $t0
sw $t0, 1200($t1)
```

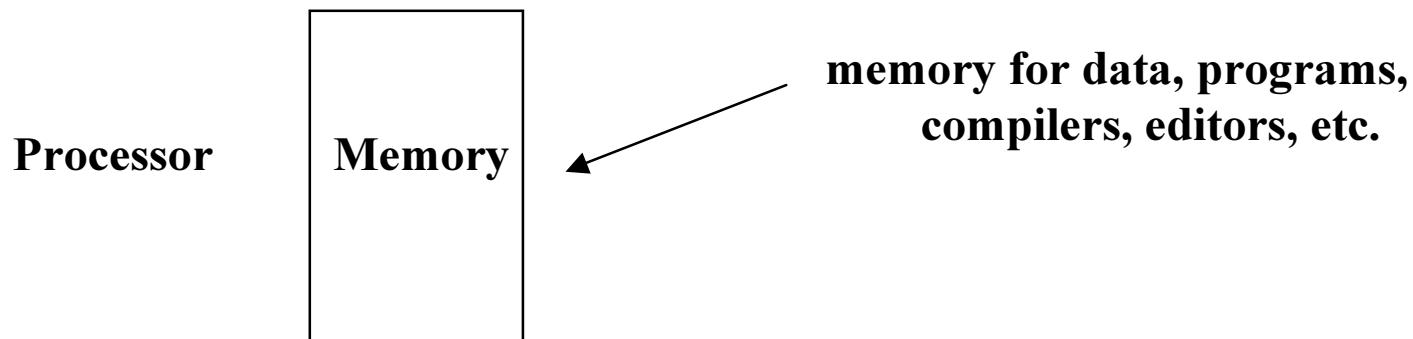
| op | rs | rt | rd | address/shamt | address/funct |
|-----------|-----------|-----------|-----------|----------------------|----------------------|
| 35 | 9 | 8 | | 1200 | |
| 0 | 18 | 8 | 8 | 0 | 32 |
| 43 | 9 | 8 | | 1200 | |

Instruções vistas até agora

| | Form. | Exemplo | | | | | | # |
|------|-------|---------|----|----|---------|-------|-------|----------------------|
| add | R | 0 | 18 | 19 | 17 | 0 | 32 | add \$s1, \$s2, \$s3 |
| sub | R | 0 | 18 | 19 | 17 | 0 | 34 | sub \$s1, \$s2, \$s3 |
| lw | I | 35 | 8 | 17 | 100 | | | lw \$s1, 100(\$s2) |
| sw | I | 43 | 8 | 17 | 100 | | | sw \$s1, 100(\$s2) |
| bits | | 6 | 5 | 5 | 5 | 5 | 6 | todas com 32 bits |
| Form | R | op | rs | rt | rd | shamt | funct | aritmética |
| Form | I | op | rs | rt | address | | | trans. dados |

Stored Program Concept

- Instructions are bits
- Programs are stored in memory
 - to be read or written just like data



- Fetch & Execute Cycle
 - Instructions are fetched and put into a special register
 - Bits in the register "control" the subsequent actions
 - Fetch the “next” instruction and continue

Control (3.5)

- **Decision making instructions**
 - alter the control flow,
 - i.e., change the "next" instruction to be executed
- **MIPS conditional branch instructions:**

```
bne $t0, $t1, Label  
beq $t0, $t1, Label
```

Example (pag 123)

- (assumir f g h i j $\Rightarrow \$s0 \rightarrow \$s4$)

```
if (i == j) goto L1;  
f = g + h;  
L1:   f = f - i;
```

```
beq $s3, $s4, Label      # goto label if i != j  
add $s0, $s1, $s2         # faz a soma  
Label: sub $s0, $s0, $$3
```

- e se não há label explícito no código C?

```
if (i != j) f = g + h;  
f = f - i;
```

assembler cria label

Control

- MIPS unconditional branch instructions:

j label

- Example:

| | |
|--|---|
| if (i!=j) h=i+j; else h=i-j; | beq \$s4, \$s5, Lab1 add \$s3, \$s4, \$s5 j Lab2 Lab1: sub \$s3, \$s4, \$s5 Lab2: ... |
|--|---|

- Can you build a simple for loop?

for (i=0; i < n; i = i + 1)

```
i <- 0
label: corpo do for
    i = i + 1
    teste (usando beq ou bne) -> label
```

So far:

- Instruction Meaning

add \$s1,\$s2,\$s3 \$s1 = \$s2 + \$s3
sub \$s1,\$s2,\$s3 \$s1 = \$s2 - \$s3
lw \$s1,100(\$s2) \$s1 = Memory[\$s2+100]
sw \$s1,100(\$s2) Memory[\$s2+100] = \$s1
bne \$s4,\$s5,L Next instr. is at Label if \$s4 ≠ \$s5
beq \$s4,\$s5,L Next instr. is at Label if \$s4 = \$s5
j Label Next instr. is at Label

- Formats:

| | | | | | | |
|---|----|----|----------------|----------------|-------|-------|
| R | op | rs | rt | rd | shamt | funct |
| I | op | rs | rt | 16 bit address | | |
| J | op | | 26 bit address | | | |

Control Flow (if then else)

```
if (i == j)          f = g + h ; else f = g - h;  
$s3 $s4           $s0 $s1 $s2
```

```
bne $s3, $s4, Else      # goto Else if i ≠ j  
add $s0, $s1, $s2       # f = g + h  
j Exit  
Else: sub $s0, $s1, $s2   # f = g - h  
Exit: ....
```

Control Flow (slt)

- **slt (set-on-less-than):**

```
if $s1 < $s2 then
    $t0 = 1
slt $t0, $s1, $s2
else
    $t0 = 0
```

- **Can use this instruction to build "blt \$s1, \$s2, Label"**
 - can now build general control structures
- **Note that the assembler needs a register to do this,**
 - there are policy of use conventions for registers

Policy of Use Conventions

| Name | Register number | Usage |
|-----------|-----------------|--|
| \$zero | 0 | the constant value 0 |
| \$v0-\$v1 | 2-3 | values for results and expression evaluation |
| \$a0-\$a3 | 4-7 | arguments |
| \$t0-\$t7 | 8-15 | temporaries |
| \$s0-\$s7 | 16-23 | saved |
| \$t8-\$t9 | 24-25 | more temporaries |
| \$gp | 28 | global pointer |
| \$sp | 29 | stack pointer |
| \$fp | 30 | frame pointer |
| \$ra | 31 | return address |

\$1 = \$at: reservado para o assembler

\$26-27 = \$k0-\$k1: reservados para o sistema operacional

Uso do \$zero

- Zero é um valor útil
- Custo em hardware é (quase) nulo
- Útil, por exemplo, para implementar
 - `mov $s1, $s2` # $\$s1 \leq \$s2$
 - `clear $s1` # $\$s1 \leq 0$
 - `blt $s1, $s2, Label` # branch on less than

Exemplo: loop com array (pag 126)

```
Loop:      g = g + A[i];          # (g      h      i      j      A)
           i = i + j;            # ($s1    $s2    $s3   $s4   $s5)
           if (i != h) goto Loop;
```

```
Loop:      add $t1, $s3, $zero    # $t1 ≤ i
           multi $t1, $t1, 4       # $t1 ≤ i * 4 (instrução adiante)
           add $t1, $t1, $s5        # $t1 ≤ i * 4 + A (posição do elemento)
           lw $t0, 0($t1)          # $t0 ≤ A[i]
           add $s1, $s1, $t0        # g ≤ g + A[i]
           add $s3, $s3, $s4        # i = i + j
           bne $s3, $s2, Loop     # goto Loop if i ≠ h
```

Exemplo: while loop (pag 127)

Loop: **while (save[i] == k) # (i j k save)**
 i = i + j; # (\$s3 \$s4 \$s5 \$s6)

Loop: **add \$t1, \$s3, \$zero # \$t1 ≤ i**
 multi \$t1, \$t1, 4 # \$t1 ≤ i * 4 (instrução adiante)
 add \$t1, \$t1, \$s6 # \$t1 ≤ i * 4 + save
 lw \$t0, 0(\$t1) # \$t0 ≤ save[i]
 bne \$t0, \$s5, Exit # goto Exit if save[i] ≠ k
 add \$s3, \$s3, \$s4 # i = i + j
 j Loop

Exit:

(ver exercício 3.9 para otimização, reduzindo para uma instrução de desvio por ciclo)

Case / switch e jr (pag 129)

```
switch (k) {  
    case 0: f=i+j; break;  
    case 1: f=g+h; break;  
    case 2: f=g-h; break;  
    case 3: f=i-j; break;  
}
```

```
# (f      g      h      i      j      k)  
# ($s0   $s1   $s2   $s3   $s4   $s5)  
# ($t2 contém o valor 4)  
# ($t4 contém base de JumpTable)
```

(testar primeiro se k dentro de 0-3)

```
add $t1, $s5, $zero          # $t1 ≤ k  
multi $t1, $t1, 4            # $t1 ≤ i * 4  
add $t1, $t1, $t4            # $t1 ≤ k * 4 + JumpTable  
lw $t0, 0($t1)              # $t0 ≤ endereço a ser saltado  
jr $t0                      # salta para o endereço  
...  
L0: add $s0, $s3, $s4        # f = i + j  
    jr Exit                  # break  
L1: add $s0, $s1, $s2        # f = g + h  
    jr Exit                  # break  
...
```

- ifs aninhados?
- quem é melhor?

Chamada de procedimentos

- Desvio: passar parâmetros, executar (salvar contexto), retornar, (recuperar contexto)
- Instrução SIMPLES do MIPS \Rightarrow jal endereço
 - desvia para endereço
 - salva “automaticamente” endereço da próxima instrução em \$ra (\$31)
- O que acontece com jal aninhados?
- Solução: pilha
 - MIPS: implementada na memória, com \$sp (\$29)
 - ver exemplos pag 134 - 139

push \$ra

```
addi    $sp, $sp, -4  
sw      $ra, 0($sp)
```

pop \$ra

```
lw      $ra, 0($sp)  
addi   $sp, $sp, 4
```

Chamada de procedimentos

- **contexto:**
 - endereço de retorno
 - registradores tipo \$sn (devem ser salvos, não podem ser alterados)
- **salvamento do contexto**
 - pelo “caller”
 - pelo “callee”
- **argumentos passados entre o chamador e o chamado**
 - usar os registradores \$a0 = \$a3
- **temporários não precisam ser salvos**

Constants

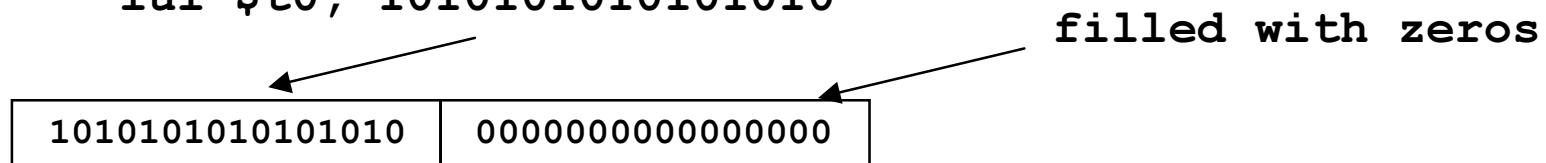
- Small constants are used quite frequently (50% of operands)
e.g., $A = A + 5;$
 $B = B + 1;$
 $C = C - 18;$
- Solutions? Why not?
 - put 'typical constants' in memory and load them.
 - create hard-wired registers (like \$zero) for constants like one.
- MIPS Instructions:

```
addi $29, $29, 4
slti $8, $18, 10
andi $29, $29, 6
ori $29, $29, 4
```
- How do we make this work?

How about larger constants?

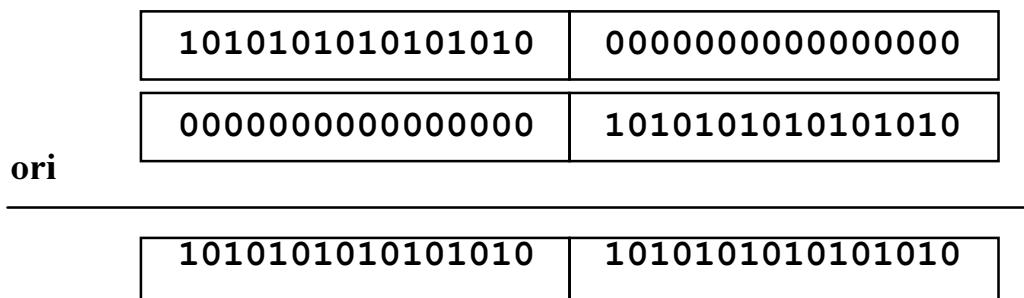
- We'd like to be able to load a 32 bit constant into a register
- Must use two instructions, new "load upper immediate" instruction

`lui $t0, 1010101010101010`



- Then must get the lower order bits right, i.e.,

`ori $t0, $t0, 1010101010101010`



Assembly Language vs. Machine Language

- **Assembly provides convenient symbolic representation**
 - much easier than writing down numbers
 - e.g., destination first
- **Machine language is the underlying reality**
 - e.g., destination is no longer first
- **Assembly can provide 'pseudoinstructions'**
 - e.g., “move \$t0, \$t1” exists only in Assembly
 - would be implemented using “add \$t0,\$t1,\$zero”
- **When considering performance you should count real instructions**

Other Issues

- **Things we are not going to cover**
linkers, loaders, memory layout
stacks, frames, recursion
manipulating strings and pointers
interrupts and exceptions
system calls and conventions
- **Some of these we'll talk about later**
- **We've focused on architectural issues**
 - basics of MIPS assembly language and machine code
 - we'll build a processor to execute these instructions.

Overview of MIPS

- simple instructions all 32 bits wide
- very structured, no unnecessary baggage
- only three instruction formats

| | | | | | | |
|---|----|----|----------------|----------------|-------|-------|
| R | op | rs | rt | rd | shamt | funct |
| I | op | rs | rt | 16 bit address | | |
| J | op | | 26 bit address | | | |

- rely on compiler to achieve performance
 - what are the compiler's goals?
- help compiler where we can

Addresses in Branches and Jumps

- **Instructions:**

| | |
|----------------------------------|--|
| <code>bne \$t4,\$t5,Label</code> | Next instruction is at Label if $\$t4 \neq \$t5$ |
| <code>beq \$t4,\$t5,Label</code> | Next instruction is at Label if $\$t4 = \$t5$ |
| <code>j Label</code> | Next instruction is at Label |

- **Formats:**

| | | | | |
|---|----|----|----|----------------|
| I | op | rs | rt | 16 bit address |
| J | op | | | 26 bit address |

- **Addresses are not 32 bits**
 - How do we handle this with load and store instructions?

Addresses in Branches

- **Instructions:**

`bne $t4,$t5,Label`
`beq $t4,$t5,Label`

Next instruction is at Label if $\$t4 \neq \$t5$

Next instruction is at Label if $\$t4 = \$t5$

- **Formats:**



- Could specify a register (like lw and sw) and add it to address
 - use Instruction Address Register (PC = program counter)
 - most branches are local (principle of locality)
- Jump instructions just use high order bits of PC
 - address boundaries of 256 MB

To summarize:

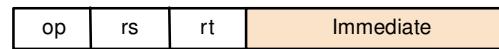
MIPS operands

| Name | Example | Comments |
|-----------------------|---|--|
| 32 registers | <code>\$s0-\$s7, \$t0-\$t9, \$zero, \$a0-\$a3, \$v0-\$v1, \$gp, \$fp, \$sp, \$ra, \$at</code> | Fast locations for data. In MIPS, data must be in registers to perform arithmetic. MIPS register \$zero always equals 0. Register \$at is reserved for the assembler to handle large constants. |
| 2^{30} memory words | Memory[0], Memory[4], ..., Memory[4294967292] | Accessed only by data transfer instructions. MIPS uses byte addresses, so sequential words differ by 4. Memory holds data structures, such as arrays, and spilled registers, such as those saved on procedure calls. |

MIPS assembly language

| Category | Instruction | Example | Meaning | Comments |
|--------------------|-------------------------|-----------------------------------|--|-----------------------------------|
| Arithmetic | add | <code>add \$s1, \$s2, \$s3</code> | $\$s1 = \$s2 + \$s3$ | Three operands; data in registers |
| | subtract | <code>sub \$s1, \$s2, \$s3</code> | $\$s1 = \$s2 - \$s3$ | Three operands; data in registers |
| | add immediate | <code>addi \$s1, \$s2, 100</code> | $\$s1 = \$s2 + 100$ | Used to add constants |
| Data transfer | load word | <code>lw \$s1, 100(\$s2)</code> | $\$s1 = \text{Memory}[\$s2 + 100]$ | Word from memory to register |
| | store word | <code>sw \$s1, 100(\$s2)</code> | $\text{Memory}[\$s2 + 100] = \$s1$ | Word from register to memory |
| | load byte | <code>lb \$s1, 100(\$s2)</code> | $\$s1 = \text{Memory}[\$s2 + 100]$ | Byte from memory to register |
| | store byte | <code>sb \$s1, 100(\$s2)</code> | $\text{Memory}[\$s2 + 100] = \$s1$ | Byte from register to memory |
| | load upper immediate | <code>lui \$s1, 100</code> | $\$s1 = 100 * 2^{16}$ | Loads constant in upper 16 bits |
| Conditional branch | branch on equal | <code>beq \$s1, \$s2, 25</code> | if ($\$s1 == \$s2$) go to PC + 4 + 100 | Equal test; PC-relative branch |
| | branch on not equal | <code>bne \$s1, \$s2, 25</code> | if ($\$s1 != \$s2$) go to PC + 4 + 100 | Not equal test; PC-relative |
| | set on less than | <code>slt \$s1, \$s2, \$s3</code> | if ($\$s2 < \$s3$) $\$s1 = 1$; else $\$s1 = 0$ | Compare less than; for beq, bne |
| | set less than immediate | <code>slti \$s1, \$s2, 100</code> | if ($\$s2 < 100$) $\$s1 = 1$; else $\$s1 = 0$ | Compare less than constant |
| Unconditional jump | jump | <code>j 2500</code> | go to 10000 | Jump to target address |
| | jump register | <code>jr \$ra</code> | go to $\$ra$ | For switch, procedure return |
| | jump and link | <code>jal 2500</code> | $\$ra = \text{PC} + 4$; go to 10000 | For procedure call |

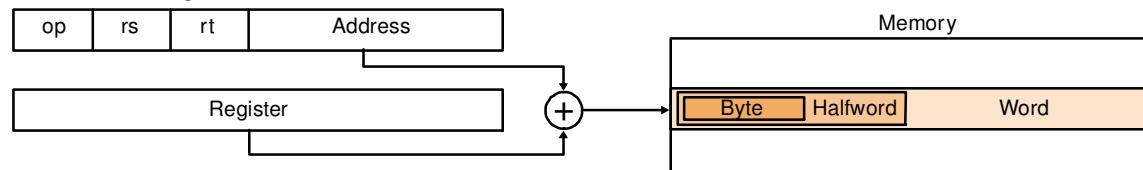
1. Immediate addressing



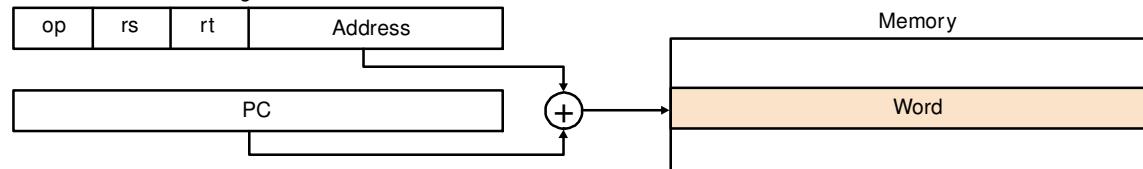
2. Register addressing



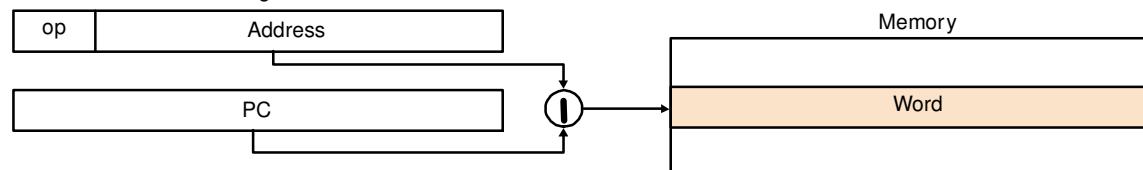
3. Base addressing



4. PC-relative addressing



5. Pseudodirect addressing



Alternative Architectures

- **Design alternative:**
 - provide more powerful operations
 - goal is to reduce number of instructions executed
 - danger is a slower cycle time and/or a higher CPI
- **Sometimes referred to as “RISC vs. CISC”**
 - virtually all new instruction sets since 1982 have been RISC
 - VAX: minimize code size, make assembly language easy
 - instructions from 1 to 54 bytes long!*
- **We'll look at PowerPC and 80x86**

Um exemplo completo

- **mostrar transparência do sort**
 - para ilustrar estrutura geral
 - não será cobrado
- **array e pointer**
 - não será cobrado

PowerPC (Motorola, Apple, IBM)

- 32 registradores de 32 bits, instruções de 32 bits
- Indexed addressing
 - example: `lw $t1,$a0+$s3` #`$t1=Memory[$a0+$s3]`
 - What do we have to do in MIPS?
- Update addressing
 - update a register as part of load (for marching through arrays)
 - example: `lwu $t0,4($s3)` #`$t0=Memory[$s3+4];$s3=$s3+4`
 - What do we have to do in MIPS?
- Others:
 - load multiple/store multiple
 - a special counter register “bc Loop”
decrement counter, if not 0 goto loop

80x86

- 1978: The Intel 8086 is announced (16 bit architecture)
- 1980: The 8087 floating point coprocessor is added
- 1982: The 80286 increases address space to 24 bits, +instructions
- 1985: The 80386 extends to 32 bits, new addressing modes
- 1989-1995: The 80486, Pentium, Pentium Pro add a few instructions
(mostly designed for higher performance)
- 1997: MMX is added

“This history illustrates the impact of the “golden handcuffs” of compatibility

“adding new features as someone might add clothing to a packed bag”

“an architecture that is difficult to explain and impossible to love”

A dominant architecture: 80x86

- See your textbook for a more detailed description
- Complexity:
 - Instructions from 1 to 17 bytes long
 - one operand must act as both a source and destination
 - one operand can come from memory
 - complex addressing modes
 - e.g., “base or scaled index with 8 or 32 bit displacement”
- Saving grace:
 - the most frequently used instructions are not too difficult to build
 - compilers avoid the portions of the architecture that are slow

*“what the 80x86 lacks in style is made up in quantity,
making it beautiful from the right perspective”*

Conclusão

- **Erro: instruções mais poderosas aumentam desempenho**
- **VAX:**
 - **CALL: salva endereço de retorno, nº de parâmetros, quaisquer registros modificados e valor antigo do SP**
 - **instrução para apagar lista duplamente ligada**
- **IBM 360:**
 - **10 instruções mais freqüentes: 80% das ocorrências**
 - **16 instruções mais freqüentes: 90% das ocorrências**
 - **21 instruções mais freqüentes: 95% das ocorrências**
 - **30 instruções mais freqüentes: 99% das ocorrências**
- **MIPS**

| classe | instr | gcc | spice |
|---------------|---------------------|-----|-------|
| arit. | add, sub, addi | 48% | 50% |
| transf. dados | lw, sw, lb, sb, lui | 33% | 41% |
| desvio cond. | beq, bne, slt, slti | 17% | 8% |
| jump | j, jr, jal | 2% | 1% |

Summary

- **Instruction complexity is only one variable**
 - lower instruction count vs. higher CPI / lower clock rate
- **Design Principles:**
 - simplicity favors regularity (facilidade de projeto)
 - smaller is faster
 - good design demands compromise
 - make the common case fast (RISC)
- **Instruction set architecture**
 - a very important abstraction indeed!

Máquinas de 0, 1, 2 e 3 endereços

$X = A * B + C * C$ onde X, A, B, C são endereços de posições de memória

Um endereço

```
LOAD A  
MULTIPLY B  
STORE T  
LOAD C  
MULTIPLY C  
ADD T  
STORE X
```

$AC \leftarrow AC \text{ op END}$

Dois endereços

```
MOVE T, A  
MULTIPLY T, B  
MOVE X, C  
MULTIPLY X, C  
ADD X, T
```

$END1 \leftarrow END1 \text{ op END2}$

Load-Store

```
load R1, A  
load R2, B  
load R3, C  
mult R1, R1, R2  
mult R3, R3, R3  
add R1, R1, R3  
store R1, X
```

$R1 \leftarrow R2 \text{ op R3}$

Três endereços

```
MULTIPLY T, A, B  
MULTIPLY X, C, C  
ADD X, X, T
```

$END1 \leftarrow END2 \text{ op END3}$

Zero endereços

```
push A  
push B  
mult  
push C  
push C  
mult  
add  
pop X
```

$tos \leftarrow tos \text{ op tos}$

Máquinas de 0, 1, 2 e 3 endereços

- Qual é o melhor?
 - tamanho do código fonte
 - tamanho do código objeto
 - tempo de execução
 - simplicidade e desempenho do hardware para suportar arquitetura