

Improved Booth-Lueker algorithm

- Does not stop when C1P violation is found
- Goes on to build PQR-tree instead
- Time complexity: almost linear
- Extra $O(\alpha(f))$ factor

Union-find (disjoint set) structure

- $make_set(x)$ $O(1)$
 - Creates new singleton set
- $find(x): r$ $O(\alpha(f))$
 - Finds representative of set containing x
- $union(r, s): t$ $O(1)$
 - Gets two representatives, unites their sets
- f = number of elements involved
- (or, number of $make_set$ operations)

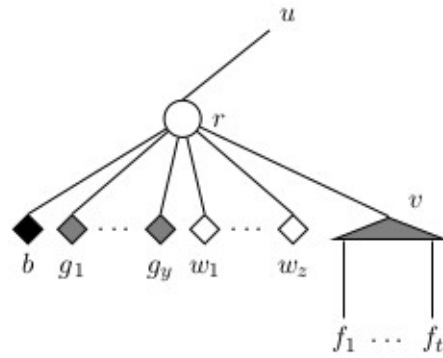
Pointers to parent

- Children of P-nodes
 - Point to their parents
- Children of Q- and R-nodes
 - Use union-find structure
 - Only representative has pointer to parent
- Advantage
 - Merging nodes with one union-find operation
- Price to pay
 - Extra *find* operation to get parent

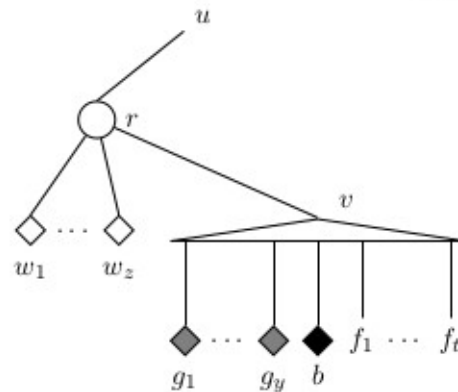
Templates

- Less cases
- All templates applied to $\text{ROOT}(T, S)$
- Can be seen as “eliminating partial nodes” while keeping consecutiveness restrictions
- If there is a partial node, $\text{ROOT}(T, S)$ is partial
- Only full or partial nodes are moved

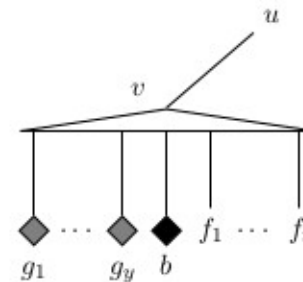
Template: P root, Q/R partial child



(a) T^v



(b) $T^{v'}$ se $z > 0$

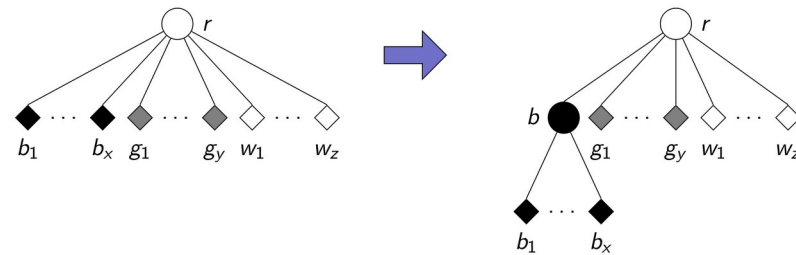


(c) $T^{v''}$ se $z = 0$

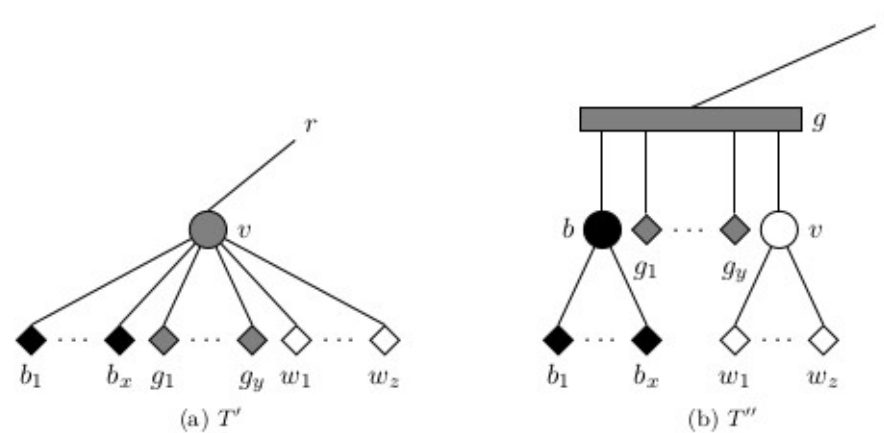
- At most one full child b in root
- Node v 's children must be ordered “darkest first”

Template: P root, Q/R partial child

- If more than one full child b in root:

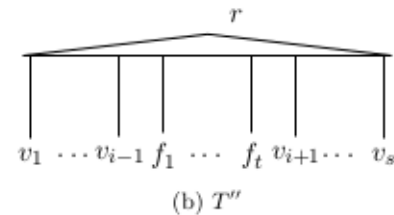
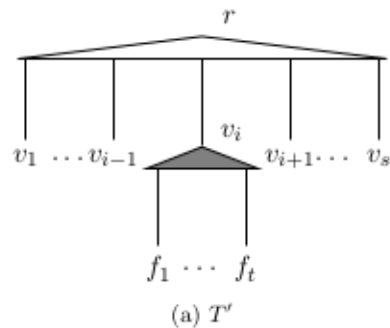


Template: P root, P partial child



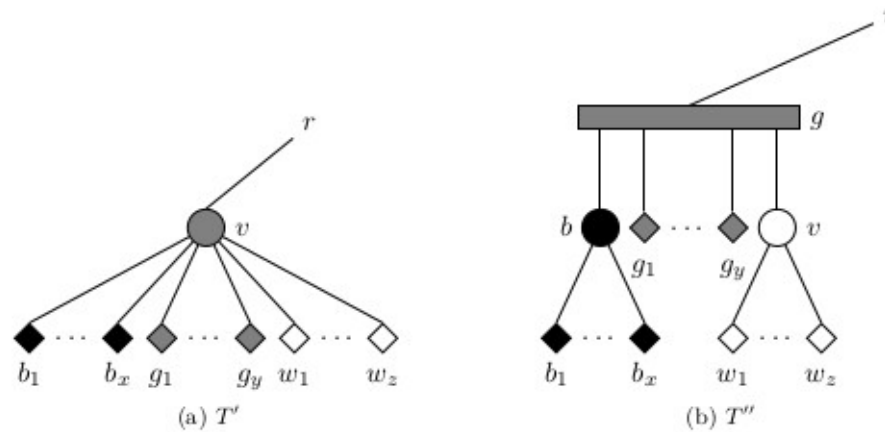
- Then apply “P root, Q/R partial child” template

Template: Q/R root, Q/R partial child



- Nodes v_{i-1} , v_{i+1} ordered “darkest first”
- Node v_i 's children ordered “darkest first”

Template: Q/r root, P partial child



- Then apply “Q/R root, Q/R partial child” template

Implementation details

- Nodes deleted from the tree must be kept for the sake of the union-find structure
- First pass (called bubble by Booth and Lueker) essentially kept, but goes on regardless of C1P: the goal is to “color” pruned nodes and find $\text{ROOT}(T, S)$
- $\text{NORM}(T)$ still applies for amortized analysis
- $\text{NORM}(T) = \# \text{ of Q/R nodes} + \# \text{ of nodes with P parent}$