## CHAPTER 4 MATLAB EXERCISES

- **1.** Let  $\mathbf{u}_1 = (1, 1, 2, 2)$ ,  $\mathbf{u}_2 = (2, 3, 5, 6)$ , and  $\mathbf{u}_3 = (2, -1, 3, 6)$ . Use MATLAB to write (if possible) the vector  $\mathbf{v}$  as a linear combination of the vectors  $\mathbf{u}_1$ ,  $\mathbf{u}_2$ , and  $\mathbf{u}_3$ .
  - (a)  $\mathbf{v} = (0, 5, 3, 0)$
  - (b)  $\mathbf{v} = (-1, 6, 1, -4)$
- **2.** Use MATLAB to determine whether the given set of vectors spans  $\mathbf{R}^4$ .
  - (a)  $\{(1, -2, 3, 4), (2, 4, 5, 0), (-2, 0, 0, 4), (3, 2, 1, -4)\}$
  - (b)  $\{(0, 1, -1, 1), (2, -2, 3, 1), (7, 0, 1, 0), (5, 2, -2, -1)\}$
- 3. Use MATLAB to determine whether the set is linearly independent or dependent.
  - (a)  $\{(0, 1, -3, 4), (-1, 0, 0, 2), (0, 5, 3, 0), (-1, 7, -3, -6)\}$
  - (b)  $\{(0,0,1,2,3),(0,0,2,3,1),(1,2,3,4,5),(2,1,0,0,0),(-1,-3,-5,0,0)\}$
- **4.** Use MATLAB to determine whether the set of vectors forms a basis of  $\mathbb{R}^4$ .
  - (a)  $\{(1, -2, 3, 4), (2, 4, 5, 0), (-2, 0, 0, 4), (3, 2, 1, -4)\}$
  - (b)  $\{(0, 1, -1, 1), (2, -2, 3, 1), (7, 0, 1, 0), (5, 2, -2, -1)\}$
  - (c)  $\{(0, 1, -3, 4), (-1, 0, 0, 2), (0, 5, 3, 0), (-1, 7, -3, -6)\}$
  - (d)  $\{(0,0,1,2),(0,2,3,1),(1,3,4,5),(2,1,0,0),(-3,-5,0,0)\}$
- 5. Suppose you want to find a basis for  $\mathbf{R}^4$  that contains the vectors  $\mathbf{v}_1 = (1, 1, 0, 0)$  and  $\mathbf{v}_2 = (1, 0, 1, 0)$ . One way to do this is to consider the set of vectors consisting of  $\mathbf{v}_1$  and  $\mathbf{v}_2$ , together with the standard basis vectors,  $\mathbf{e}_1 = (1, 0, 0, 0)$ ,  $\mathbf{e}_2 = (0, 1, 0, 0)$ ,  $\mathbf{e}_3 = (0, 0, 1, 0)$ , and  $\mathbf{e}_4 = (0, 0, 0, 1)$ . Let A be the matrix whose columns consist of the vectors  $\mathbf{v}_1$ ,  $\mathbf{v}_2$ ,  $\mathbf{e}_1$ ,  $\mathbf{e}_2$ ,  $\mathbf{e}_3$ , and  $\mathbf{e}_4$ , and apply **rref** to A to obtain

$$A = \begin{bmatrix} 1 & 1 & 1 & 0 & 0 & 0 \\ 1 & 0 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix} \longrightarrow \begin{bmatrix} 1 & 0 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & -1 & -1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix}.$$

Since the leading ones of the reduced matrix on the right are in columns 1, 2, 3, and 6, a basis for  $\mathbb{R}^4$  consists of the corresponding column vectors of  $A: \{\mathbf{v_1}, \mathbf{v_2}, \mathbf{e_1}, \mathbf{e_4}\}$ .

A convenient way to construct the matrix A is to define the matrix B whose columns are the given vectors  $\mathbf{v}_1$  and  $\mathbf{v}_2$ . Then A is simply the matrix obtained by adjoining the  $4 \times 4$  identity matrix to  $B: A = [B \quad \text{eye}(4)]$ .

Use this algorithm to find a basis for  $\mathbb{R}^5$  that contains the given vectors.

- (a)  $\mathbf{v}_1 = (2, 1, 0, 0, 0), \quad \mathbf{v}_2 = (-1, 0, 1, 0, 0),$
- (b)  $\mathbf{v}_1 = (1, 0, 2, 0, 0), \quad \mathbf{v}_2 = (1, 1, 2, 0, 0), \quad \mathbf{v}_3 = (1, 1, 1, 0, 1)$
- **6.** Use MATLAB to find a subset of the given set of vectors that forms a basis for the span of the vectors.
  - (a)  $\{(1, 2, -1, 0), (-3, -6, 3, 0), (1, 0, 0, 1), (-2, -2, 1, -1)\}$
  - (b)  $\{(0,0,1,1,0),(1,1,0,0,1),(1,1,1,1,1),(1,1,2,2,1),(0,0,3,3,1),(0,0,0,0,1)\}$

$$A = \begin{bmatrix} -1 & 2 & 0 & 0 & 3 \\ 0 & 2 & 3 & -1 & 2 \\ -1 & 4 & 3 & -1 & 5 \\ 2 & -4 & 0 & 0 & -6 \\ 0 & 0 & 0 & 1 & 1 \end{bmatrix}.$$

- (a) Find a basis for the row space of A.
- (b) Find a basis for the column space of A.
- (c) Use the MATLAB command **rank** to find the rank of A.
- **8.** Find a basis for the nullspace of the given matrix *A*. Then verify that the sum of the rank and nullity of *A* equals the number of columns.

(a) 
$$A = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 5 & 6 & 7 & 8 \\ 9 & 10 & 11 & 12 \\ 13 & 14 & 15 & 16 \end{bmatrix}$$

- (b) A = hilb(5)
- (c) A = pascal(5)
- (d) A = magic(6)
- **9.** Let  $\{(1,0,1), (0,-1,2), (2,3,-5)\}$  be a (nonstandard) basis for  $\mathbb{R}^3$ . You can find the coordinate matrix of  $\mathbf{x} = (1,2,-1)$  relative to this basis by writing  $\mathbf{x}$  as a linear combination of the basis vectors. That is, the coordinate matrix is the solution vector to the linear system  $B\mathbf{c} = \mathbf{x}$ , where the basis vectors form the columns of B. Use MATLAB to solve this system and compare your answer to Section 4.7, Example 3.
- **10.** Let  $B = \{(1, 0, 0), (0, 1, 0), (0, 0, 1)\}$  and  $B1 = \{(1, 0, 1), (0, -1, 2), (2, 3, -5)\}$  be the two bases of  $R^3$  given in Section 4.7, Example 4. We can use MATLAB to find the transition matrix from B to B1 by first forming the two matrices

$$B = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad \text{and} \quad B1 = \begin{bmatrix} 1 & 0 & 2 \\ 0 & -1 & 3 \\ 1 & 2 & -5 \end{bmatrix}.$$

Adjoin B and B1 by using the MATLAB command  $C = [B1 \ B]$ . Let A be the reduced row-echelon form of C, A = rref(C). Finally,  $PINV = P^{-1}$  is obtained by deleting the first three columns of this reduced matrix using the MATLAB command PINV = A(:,4:6). You obtain P simply by inverting PINV.

Find the transition matrix from B to B1.

(a) 
$$B = \{(-3, 2), (4, -2)\}, B1 = \{(-1, 2), (2, -2)\}.$$

(b) 
$$B = \{(1, 1, 1, 1), (0, 1, 1, 1), (0, 0, 1, 1), (0, 0, 0, 1)\},\$$

$$B1 = \{(1, 0, 1, 0), (1, 0, -1, 0), (0, 1, 0, 1), (0, 1, 0, -1)\}$$